

C10

Origin on the non-motor side is selectable: Lead 20 • 10



Ordering method

C10

Model	Lead	Brake	Option	Stroke	Cable length ^{Note 2}
	20: 20mm 10: 10mm 5: 5mm	No entry: With no brake BK: With brake	Origin position change None: Standard Z: Non-motor side ^{Note 1}	150 to 1050 (50mm pitch)	3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable)

TSX

Positioner ^{Note 3}	Driver: Power-supply voltage / Power capacity	Regenerative unit	LCD monitor	I/O selection	Battery
TS-X	105: 100V/100W or less 205: 200V/100W or less	No entry: None R: With RGT	No entry: None L: With LCD	NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ PT: PROFINET GW: No I/O board ^{Note 4}	B: With battery (Absolute) N: None (Incremental)

SR1-X

Controller	Driver: Power capacity	Usable for CE	Regenerative unit	I/O selection	Battery
05	05: 100W or less	No entry: Standard E: CE marking	No entry: None R: With RGT	N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS	B: With battery (Absolute) N: None (Incremental)

RDV-X

Driver	Power-supply voltage	Driver: Power capacity	Regenerative unit
2	2: AC200V	05: 100W or less	RBR1

- Note 1. If selecting 5mm lead specifications then the origin point cannot be changed to the non-motor side.
 Note 2. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.594 for details on robot cable.
 Note 3. See P.498 for DIN rail mounting bracket.
 Note 4. Select this selection when using the gateway function. For details, see P.60.

Basic specifications

AC servo motor output (W)	100
Repeatability ^{Note 1} (mm)	+/-0.01
Deceleration mechanism	Ball screw (Class C7)
Ball screw lead (mm)	20 10 5
Maximum speed (mm/sec)	1000 500 250
Maximum payload (kg)	Horizontal 20 40 60 Vertical 4 10 20
Rated thrust (N)	84 169 339
Stroke (mm)	150 to 1050 (50mm pitch)
Overall length (mm)	Horizontal Stroke+283 Vertical Stroke+313
Maximum outside dimension of body cross-section (mm)	W104 x H85
Cable length (m)	Standard: 3.5 / Option: 5, 10
Degree of cleanliness	CLASS 10 ^{Note 3}
Intake air (Nl/min)	30 to 90 ^{Note 4}

- Note 1. Positioning repeatability in one direction.
 Note 2. When the stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.
 Note 3. Per 1cf (0.1um base), when suction blower is used.
 Note 4. The necessary intake amount varies depending on the use conditions and environment.

Allowable overhang^{Note}

Installation	Lead	Horizontal installation (Unit: mm)			Wall installation (Unit: mm)			Vertical installation (Unit: mm)				
		A	B	C	A	B	C	A	C			
Horizontal	Lead 20	5kg	1875	530	510	5kg	496	451	1826	1kg	2461	2492
	Lead 10	10kg	1079	247	242	10kg	218	168	1002	2kg	1213	1244
	Lead 5	20kg	628	106	107	20kg	78	27	497	4kg	585	617
	Lead 20	15kg	765	156	164	10kg	230	170	1036	8kg	627	658
	Lead 10	30kg	425	62	66	20kg	80	29	506	10kg	280	312
Wall	Lead 10	40kg	350	38	42	10kg	30	0	311	15kg	210	242
	Lead 5	30kg	960	63	68	10kg	234	170	2716	10kg	213	244
	Lead 20	50kg	565	25	28	20kg	82	29	1206	15kg	119	151
	Lead 10	60kg	470	16	17	30kg	31	0	711	20kg	72	104
	Lead 5	30kg	82	29	1206	30kg	31	0	711			

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment

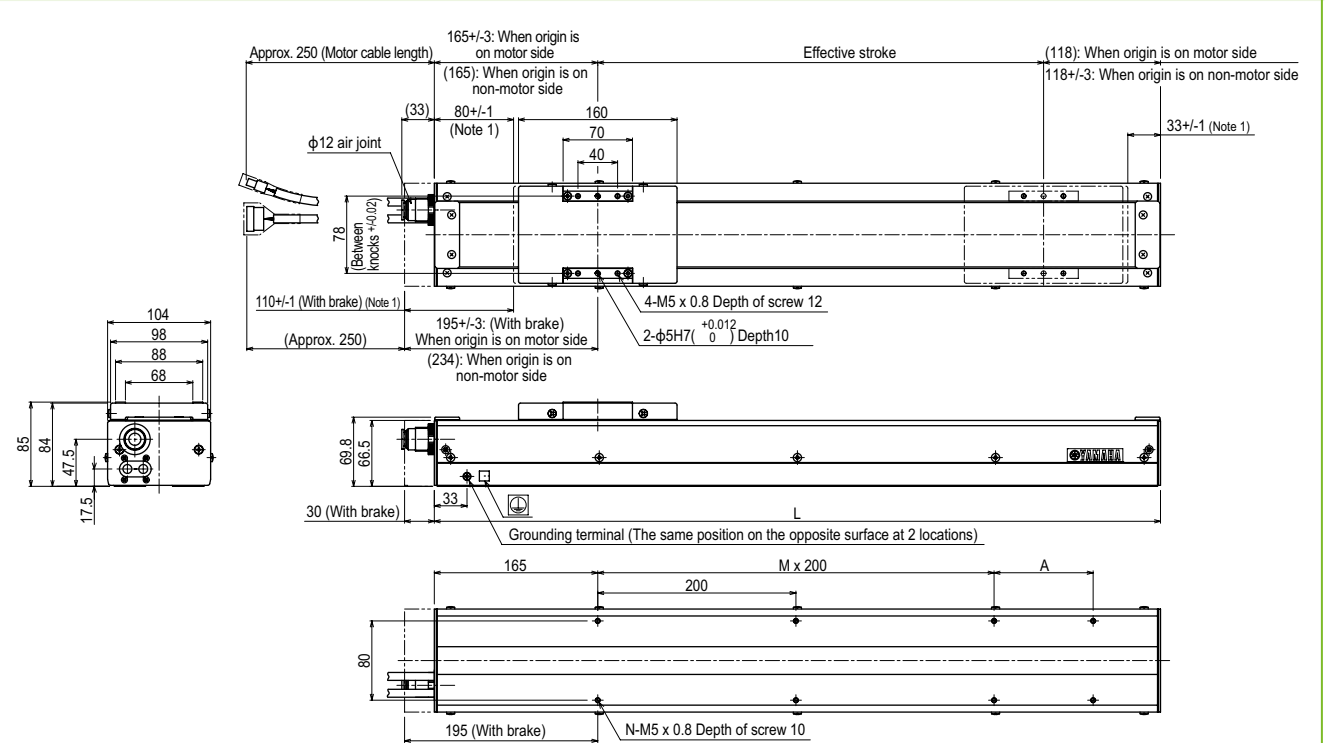
(Unit: N·m)		
MY	MP	MR
119	119	105

Controller

Controller	Operation method
SR1-X05 ^{Note}	Programming / I/O point trace / Remote command / Operation using RS-232C communication
TS-X105 ^{Note}	I/O point trace / Remote command
TS-X205 ^{Note}	I/O point trace / Remote command
RDV-X205-RBR1	Pulse train control

Note. Regenerative unit is required when the models used vertically and with 700mm or larger stroke.

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Effective stroke	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	
L	433	483	533	583	633	683	733	783	833	883	933	983	1033	1083	1133	1183	1233	1283	1333	
A	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	
M	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	
N	4	6	6	6	6	8	8	8	8	10	10	10	10	12	12	12	12	14	14	
Weight (kg) ^{Note 3}	4.4	5.0	5.5	6.1	6.7	7.3	7.8	8.4	9.0	9.6	10.1	10.7	11.3	11.9	12.4	13.0	13.6	14.2	14.7	
Maximum speed (mm/sec) ^{Note 4}	Lead 20	1000																		
	Lead 10	500																		
	Lead 5	250																		
Speed setting	95% 95% 75% 75% 60% 60% 50%																			

Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. Minimum bend radius of motor cable is R50.
 Note 3. Weight of models with no brake. The weight of brake-attached models is 0.4 kg heavier than the models with no brake shown in the table.
 Note 4. When the stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.