

F14H

● High lead: Lead 30

● Origin on the non-motor side is selectable: Lead 10-20-30

Note. Strokes longer than 1050mm are special order items. Please consult us for delivery time.



Ordering method

Model	Lead designation	Brake	Cable entry location	Origin position change	Grease type	Stroke	Cable length
F14H	30: 30mm 20: 20mm 10: 10mm 5: 5mm	No entry: No brakes BK: Brakes provided	No entry: Standard (S) U: From the top R: From the right L: From the left	None: Standard Z: Non-motor side	None: Standard GC: Clean	Lead 20: 10-5: 150 to 1050 (50mm pitch) Lead 30: 150 to 1250 (50mm pitch)	3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable)

- Note 1. The model with a lead of 30mm cannot select specifications with brake (vertical specifications).
 Note 2. If selecting 5mm lead specifications then the origin point cannot be changed to the non-motor side.
 Note 3. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.594 for details on robot cable.
 Note 4. See P.498 for DIN rail mounting bracket.
 Note 5. Select this selection when using the gateway function. For details, see P.60.

TSX	SR1-X	RDV-X	RBR1
Positioner TS-X	Controller SR1-X	Driver RDV-X	Regenerative unit RBR1
Driver: Power-supply voltage Power capacity 110: 100V/200W 210: 200V/200W	Driver: Power capacity 10: 200W	Power-supply voltage 2: AC200V	Driver: Power capacity 10: 200W or less
Regenerative unit No entry: None R: With RGT	Usable for CE No entry: Standard E: CE marking		Regenerative unit No entry: None R: With RGT
LCD monitor No entry: None L: With LCD			
I/O selection NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ PT: PROFINET GW: No I/O board	I/O selection N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS		I/O selection N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS
Battery B: With battery N: None (Incremental)	Battery B: With battery (Absolute) N: None (Incremental)		Battery B: With battery (Absolute) N: None (Incremental)

Specifications

AC servo motor output (W)	200
Repeatability (mm)	+/-0.01
Deceleration mechanism	Ball screw (Class C7)
Ball screw lead (mm)	30 20 10 5
Maximum speed (mm/sec)	1800 1200 600 300
Maximum payload (kg)	Horizontal: 25 40 80 100 Vertical: - 8 20 30
Rated thrust (N)	113 170 341 683
Stroke (mm)	150 to 1250 (50mm pitch)
Overall length (mm)	Horizontal: Stroke+320 Vertical: Stroke+350
Maximum dimensions of cross section of main unit (mm)	W136 x H83
Cable length (m)	Standard: 3.5 / Option: 5.10
Linear guide type	4 rows of circular arc grooves x 2 rail
Position detector	Resolvers
Resolution (Pulse/rotation)	16384

- Note 1. Positioning repeatability in one direction.
 Note 2. When the stroke is longer than 700mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.
 Note 3. Strokes longer than 1050mm are available only for high lead (Lead 30). (Special order item)
 Note 4. Position detectors (resolvers) are common to incremental and absolute specifications. If the controller has a backup function then it will be absolute specifications.

Allowable overhang

Installation	Lead	Weight	A	B	C
Horizontal installation (Unit: mm)	Lead 30	10kg	2152	1673	934
		25kg	1847	691	533
		40kg	1047	445	324
	Lead 20	10kg	2265	1674	961
		20kg	1402	855	537
		40kg	1047	445	324
Wall installation (Unit: mm)	Lead 30	10kg	975	1219	1625
		25kg	482	426	1257
		40kg	263	227	635
	Lead 20	10kg	999	1220	1711
		20kg	515	558	987
		40kg	263	227	635
Vertical installation (Unit: mm)	Lead 10	4kg	2400	2016	
		6kg	1699	1364	
		8kg	1301	1051	
	Lead 5	10kg	1370	1106	
		20kg	906	732	
		30kg	678	548	

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment

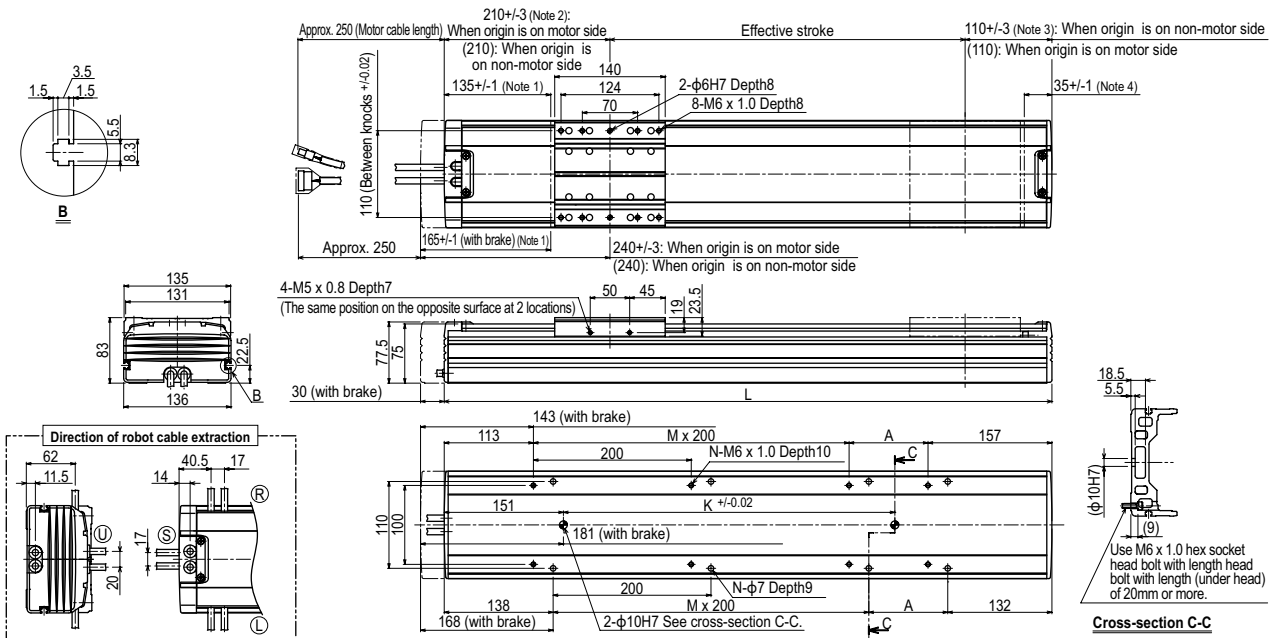
Direction	MY	MP	MR
(Unit: N-m)	551	552	485

Controller

Controller	Operation method
SR1-X10 RCX221/222 RCX240/340	Programming / I/O point trace / Remote command / Operation using RS-232C communication
TS-X110 TS-X210 RDV-X210-RBR1	I/O point trace / Remote command / Pulse train control

Note. When using the unit vertically, a regeneration unit is required.

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Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. 212.5+/-4 when the high lead specification (Lead 30) is used.
 Note 3. 110+/-4 when the high lead specification (Lead 30) is used.
 Note 4. 32.5+/-1 when the high lead specification (Lead 30) is used.
 Note 5. Minimum bend radius of motor cable is R50.
 Note 6. Weight of models with no brake. The weight of brake-attached models is 0.7 kg heavier than the models with no brake shown in the table.
 Note 7. When the stroke is longer than 700mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table above.
 Note 8. Strokes longer than 1050mm are special order items. Please contact us for speed setting.

Effective stroke	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	1250
L	470	520	570	620	670	720	770	820	870	920	970	1020	1070	1120	1170	1220	1270	1320	1370	1420	1470	1520	1570
A	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100
M	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5	5	5	6	6
N	4	6	6	6	6	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16
K	240	240	240	420	420	420	600	600	600	600	600	780	780	960	960	960	960	1140	1140	1140	1140	1140	1320
Weight (kg)	7.5	8.2	8.8	9.5	10.1	10.8	11.4	12.1	12.7	13.4	13.9	14.6	15.2	15.9	16.5	17.2	17.8	18.5	19.1	19.8	20.4	21.1	21.7
Lead 30	1800												1440	1170			900		810				
Lead 20							1200						960	780			600		540				
Lead 10							600						480	390			300		270				
Lead 5							300						240	195			150		135				
Speed setting													80%	65%			50%		45%				

Controller

SR1-X ▶ 516

TS-X ▶ 490

RDV-X ▶ 504