

HXYx 2 axes

Moving arm type Cable carrier

Ordering method

HXYx - C	[]	[]	[]	[]	RCX222HP	[]	R	[]	[]
Model	Cable	Combination	X-axis stroke	Y-axis stroke	Cable length	Controller	Usable for CE	Regenerative unit	Input/Output selection 1

M1	25 to 125cm	25 to 65cm	No entry: Standard 5L: 5m 10L: 10m
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RCX222HP	DRCX2020	No entry: Standard E: CE marking
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R: RG2 (RCX222HP)	R: RGU-2 (DRCX)
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Input/Output selection 1	Input/Output selection 2
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N: NPN Note 1	No entry: None
P: PNP	N1: OP.DIO24/16 (NPN) Note 1
CC: CC-Link	Pt: OP.DIO24/17 (PNP)
DN: DeviceNet	EN: Ethernet Note 1
PB: Profibus	VC: YC-Link Note 2
EN: Ethernet	EN: Ethernet Note 3

Note 1. NPN and Ethernet cannot be selected if using CE marking.

Note 2. Available only for the master.

Note 3. Only when CC or DN or PB was selected for I/O select 1 above, EN can be selected in I/O select 2.

Specification

	X-axis	Y-axis
Axis construction Note 1	F20	F17
AC servo motor output (W)	600	400
Repeatability Note 2 (mm)	+/-0.01	+/-0.01
Drive system	Ball screw (Class C7)	Ball screw (Class C7)
Ball screw lead (Deceleration ratio) (mm)	20	20
Maximum speed Note 3 (mm/sec)	1200	1200
Moving range (mm)	250 to 1250	250 to 650
Robot cable length (m)	Standard: 3.5 Option: 5,10	

Note 1. Use caution that the flame machining (installation holes, tap holes) differs from single-axis robots'.

Note 2. Positioning repeatability in one direction.

Note 3. When the X-axis stroke is longer than 850mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.

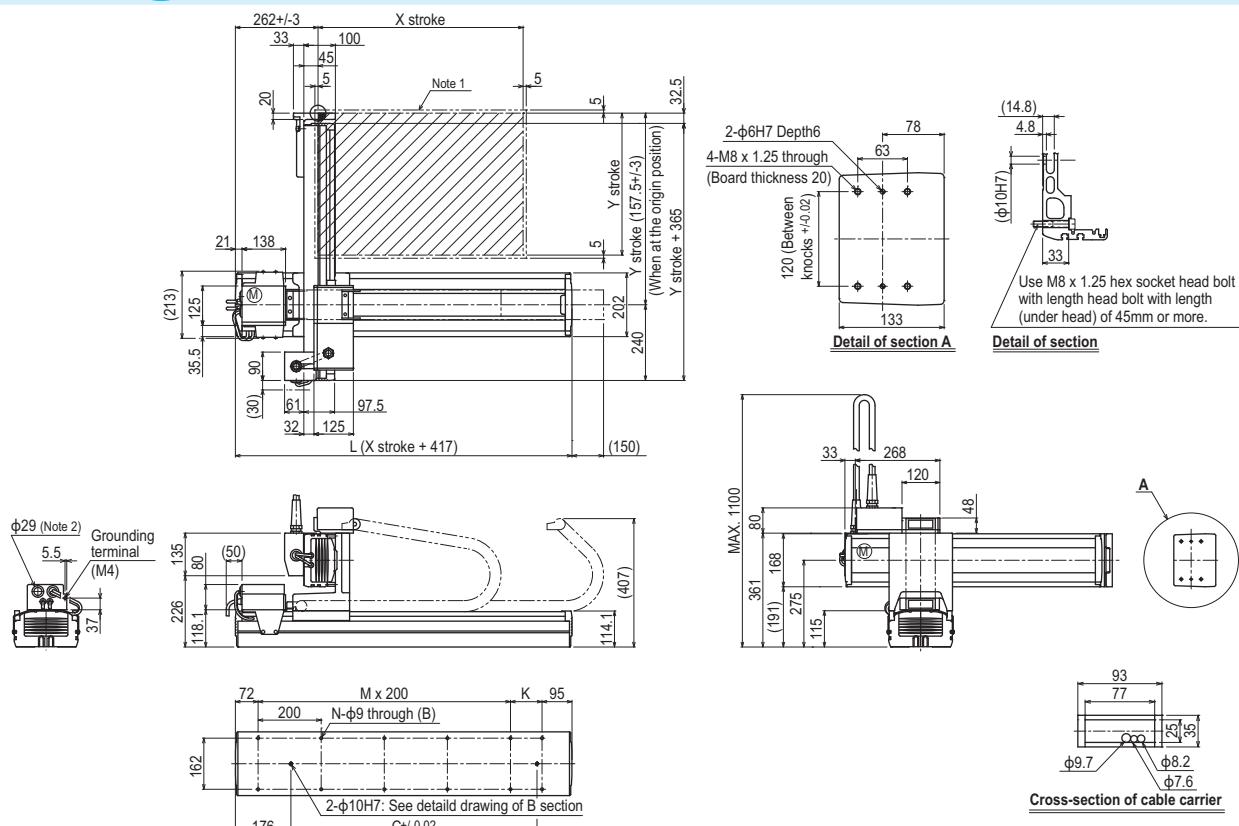
Maximum payload

Y stroke (mm)	XY 2 axes
250 to 650	30

Controller

Controller	Operation method
RCX222HP-R	Programming / I/O point trace / Remote command / Operation using RS-232C communication
DRCX2020-R	

HXYx 2 axes M1



X stroke	250	350	450	550	650	750	850	950	1050	1150	1250
L	667	767	867	967	1067	1167	1267	1367	1467	1567	1667
K	100	200	100	200	100	200	100	200	100	200	100
C	420	420	600	600	780	780	960	960	1140	1320	1320
M	2	2	3	3	4	4	5	5	6	6	7
N	8	8	10	10	12	12	14	14	16	16	18

Y stroke

X-axis	1200	960	840	720	600	480
Speed setting	-	80%	70%	60%	50%	40%

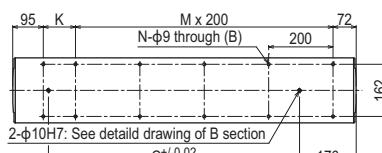
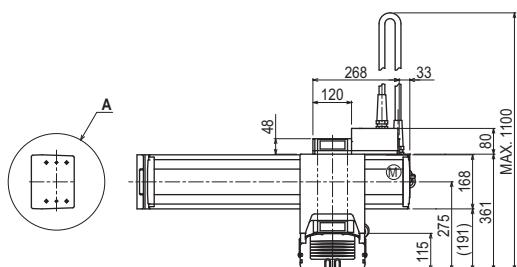
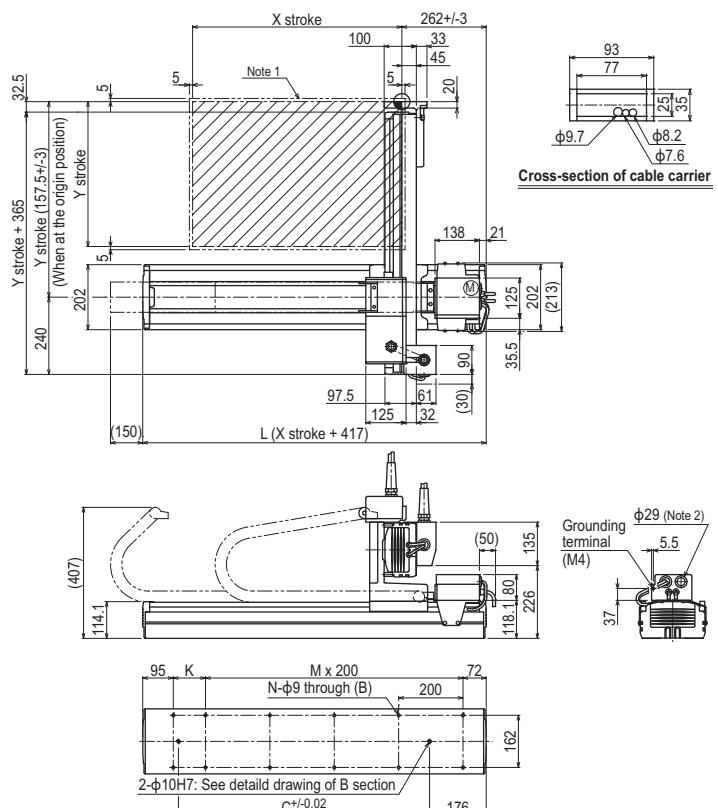
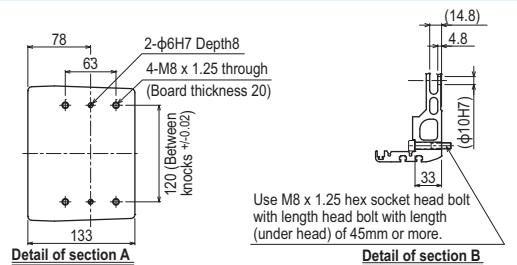
Note 1. The moving range when returning to origin and the stop position when stopping by the mechanical stopper.

Note 2. User cable extraction port.

Note 3. When the X-axis stroke is longer than 850mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.

APPLICATION	Compact single-axis robots
TRANSEROV	Single-axis robots
FLIP-X	Linear motor single-axis robots
PHASER	Cartesian robots
X-Y-X	SCARA robots
YK-XG	Pick & place robots
YP-X	Clean
CLEAN	Controller
CONTROLLER	Information
INFORMATION	Arm type
	Gantry type
	Moving arm type
	Pole type
	XZ type

HXYx 2 axes M3



X stroke	250	350	450	550	650	750	850	950	1050	1150	1250
L	667	767	867	967	1067	1167	1267	1367	1467	1567	1667
K	100	200	100	200	100	200	100	200	100	200	100
C	420	420	600	600	780	780	960	960	1140	1320	1320
M	2	2	3	3	4	4	5	5	6	6	7
N	8	8	10	10	12	12	14	14	16	16	18

Y stroke 250 350 450 550 650

Maximum speed for each stroke(mm/sec)	X-axis Speed setting	1200	960	840	720	600	480
Note 3	-	80%	70%	60%	50%	40%	

Note 1. The moving range when returning to origin and the stop position when stopping by the mechanical stopper.

Note 2. User cable extraction port.

Note 3. When the X-axis stroke is longer than 850mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.