YP220BX 2axes

■ Ordering method

YP220BX

Cable length

RCX222

Usable for CE

Inputs/Outputs s N: NPN Note: P: PNP

Inputs/Outputs selection 2 No entry: None
N1: OP.DIO24/16
(NPN) Note 2
P1: OP.DIO24/17
(PND)

Note 1. Available only for the master.

Note 2. NPN cannot be selected if using CE marking.

Note 3. Only when you have selected CC, DN or PB for Input/Output selection 1, you can select EN for Input/Output selection 2.

	X axis	Z axis
AC servo motor output (W)	200	200
Repeatability Note 1 (mm)	+/-0.05	+/-0.05
Drive system	Timing belt	Timing belt
Deceleration ratio (mm)	Equivalent to lead 24	Equivalent to lead 20
Maximum speed Note 2 (mm/sec)	1440	1200
Moving range (mm)	200	100
Cycle time (sec)	0.45 Note 3	
Maximum payload (kg)	3	
Robot cable length (m)	Standard: 3.5 Option: 5,10	
Weight (kg)	17	

Note 1. Positioning repeatability precision in a single swing when residual vibration is stabilized (variable depending on the load and stroke).

Note 2. When the moving stroke is short, the maximum speed may not be reached.

Note 3. Reciprocating time in vertical direction (50mm) and longitudinal direction (150mm) with the arch amount of 50 (when executing rough-positioning arch motion with 1kg load).

■ Controller			
Controller	Power consumption (VA)	Operating method	
RCX222	500	Programming / I/O point trace / Remote command / Operation using RS-232C communication	

